ROTARY STAGES APR SERIES



APR stages are perfect for rotary testing, pointing, optical calibration systems and metrology systems.

Aerotech's APR series direct-drive rotary stage is excellent for high-accuracy rotary positioning. The precision-machined and ground stage parts coupled with high-precision angular contact bearings result in exceptionally low error motions, accuracy errors, and repeatability errors. In addition, high resolution optical encoders provide excellent pointing capability with low-jitter velocity tracking.

Applications

The APR stages are perfect for rotary testing, pointing, optical calibration systems, and metrology systems. Several more specific applications include single and multi-axis electro-optic sensor testing, resolver or optical encoder accuracy testing, missile seeker testing, antenna testing, inertial navigation device testing, photonic component alignment, high-accuracy laser machining, and precision wafer inspection. Multiple APR stages can be combined for high-accuracy azimuth/elevation or azimuth/roll systems. Vacuum-prepared and other customized versions are also available for specialized applications.

Accurate Positioning with Incremental or Absolute Encoders

The APR provides the flexibility of using high-resolution absolute or incremental optical encoders. The absolute encoder option allows instant initialization at the time of power up and eliminates the need for a home cycle. Incremental encoders are available for a cost-effective, accurate, high resolution, high dynamic performance stage. Both incremental and absolute encoders provide exceptional accuracy and fine stepping capability. The APR stages are available with high-accuracy encoder options. In addition, calibration can be employed to further improve the accuracy of all APR stages.

Superior Mechanical Design

The motor and high-performance encoder are directly coupled to a common shaft, and the absence of gears, belts, or other drive-train mechanisms results in elimination of position error caused by hysteresis, windup, or backlash. Precision machining and grinding techniques used on the stage parts, along with precision angular contact bearings, ensure that tilt (wobble), axial, and radial error motions are minimized. An optional tabletop provides a larger surface area and an expanded hole pattern for payload mounting and allows for configurable limited travel options up to 270°. The tabletop options also include angular graduation marks

for easy visual recognition of the stage position.

Low Total Indicator Runout (TIR) Mounting Surfaces

On standard APR stages, the payload is mounted directly to the precision-ground stage shaft via an eight-bolt hole pattern on the top of the shaft. The top surface and the aperture of the shaft are precision–machined for minimal surface runout with respect to stage motion. Precision-ground tabletop options provide more traditional metric or English hole-patterns while maintaining low surface runout of the tabletop mounting surface and aperture.

High Speed, High Bandwidth

Rapid acceleration and high velocity are key features of the APR stages. Customers can command rapid incremental or continuous rotary motion with the high-torque brushless motors in the APRs. Due to the direct-drive motor and the stage's high stiffness, the APR can provide high-bandwidth motion for oscillations, motion profiling, and rapid position or velocity tracking.

- PRODUCT HIGHLIGHTS -

Accuracy to 1.5 arc sec and repeatability to 0.5 arc sec make APR the most precise mechanical-bearing rotary stage available

Ample load capacity up to 250 kg and high moment stiffness support large payloads in both horizontal and vertical orientations

Continuous rotation speed up to 1500 rpm with excellent velocity stability

Brushless, cogless direct-drive motor provides extremely smooth motion in high-speed and high-torque configurations

Optional fail-safe holding brake, limited travel configurations, and absolute encoder provide additional payload security and mitigate inadvertent crash risks



Brushless Direct-Drive

To maximize positioning performance, the APR series utilizes Aerotech's brushless, slotless motors. Various winding options and motor stack heights are available for applications ranging from high-speed at a low input voltage or low current to high torque at a higher voltage. The motors are noncontact, so there are no brushes or gears to maintain. This allows the APR stages to provide many years of high performance operation with low cost of ownership. The motor's slotless, ironless construction features almost zero cogging (torque ripple). This makes the APR ideal for applications requiring outstanding contoured motion, smooth scan velocity, and precision motion profiling.

High Load Capacity and Large Moment Stiffness

Sturdy stage construction and separated angular contact bearings result in large load capacity and high moment stiffness for the APR stages. The APRs can excel in applications where the rotation axis is parallel or perpendicular to gravity and the payload center of gravity is cantilevered away from the stage.

Flexible Controller Configurations

Aerotech designs and manufactures a wide range of servo amplifiers and advanced controllers to provide a complete, integrated electro-mechanical package. Aerotech linear amplifiers provide the most precise positioning for demanding accuracy and in-position stability. Aerotech PWM digital drives provide high power for rapid acceleration and high torque applications. Whatever your application, Aerotech can provide a complete motion system solution to perfectly match your requirements.

Specifications		APR100DR-095	APR100DR-145		
Travel			Continuous (Optional 270° Max Limited)		
-E1, -E2, -E3, -E4		Uncalibrated	45 arc sec		
A	Feedback Options	Calibrated	4 arc s	ec	
Accuracy	-E5, -E6 Feedback	Uncalibrated	4 arc sec		
	Options	Calibrated	2 arc sec		
Resolution (Minimur	n Incremental Motion		0.1 arc	sec	
Repeatability (Bi-Dir	ectional)¹		1.5 arc :	sec	
Repeatability (Uni-D	irectional)		0.75 arc	sec	
Total Tilt Error Motio	on²		2 arc sec		
Total Axial Error Mot	tion ²		1.5 μm		
Total Radial Error Motion ²			1.5 μm		
With -M1 Motor Option		ion	1500 rpm		
Maximum Speed ³	Maximum Speed ³ With -M2 Motor Opti		TBD		
Aperture			15 mm		
Maximum Torque (C	ontinuous)		0.48 Nm	1.6 Nm	
Load Capacity Axial Radial			30 kg		
		25 kg			
Rotor Inertia (Unloaded)			0.0006 kg-m²	0.0009 kg-m²	
Stage Mass ⁴			3.2 kg 5.6 kg		
Material			Aluminum; Hardcoat/Anodize Finish		
MTBF (Mean Time Between Failure)		20,000 hours			

- 1 Certified with each stage.
- 2 All error motion specifications are measured at 60 rpm.
- 3 Maximum speed listed is stage and motor dependent (assuming a 340 V bus). Actual speed may be lower due to motor back emf or encoder bandwidth (see Encoder Bandwidth table). Consult an Aerotech Applications Engineer for more details.
- 4 Mass listed is for the standard stage option (no brake and no tabletop). Consult Aerotech if brake and tabletop masses are desired.

Specifications		APR150DR-115	APR150DR-135	APR150DR-180		
Travel		Continuous (Optional 270° Max Limited)				
	-E1, -E2, -E3, -E4	Uncalibrated	45 arc sec			
_	Feedback Options	Calibrated	4 arc sec			
Accuracy	-E5, -E6 Feedback	Uncalibrated	N/A 4 arc sec			
	Options	Calibrated	N/A 2 arc sec		c sec	
Resolution (Minimum	n Incremental Motion			.08 arc sec		
Repeatability (Bi-Dire	ectional)¹			1.5 arc sec		
Repeatability (Uni-Di	rectional)		0.75 arc sec			
Total Tilt Error Motio	n²		2 arc sec			
Total Axial Error Mot	ion²		1.5 µm			
Total Radial Error Motion ²		1.5 μm				
With -M1 Motor		ion	600 rpm			
Maximum Speed ³	With -M2 Motor Option		800 rpm			
Aperture			50mm			
Maximum Torque (Continuous)			2.85 Nm	5.06 Nm	9.29 Nm	
Load Canasity	Axial		45 kg			
Load Capacity Radial		32 kg				
Rotor Inertia (Unloaded)		0.0047 kg-m²	0.006 kg-m²	0.0086 kg-m²		
Stage Mass ⁴		6.5 kg 8.5 kg 12.3 kg				
Material		Aluminum; Hardcoat/Anodize Finish				
MTBF (Mean Time Between Failure)		20,000 hours				

- Certified with each stage.
- All error motion specifications are measured at 60 rpm.

 Maximum speed listed is stage and motor dependent (assuming a 340 V bus). Actual speed may be lower due to motor back emf or encoder bandwidth (see Encoder Bandwidth table).

 Consult an Aerotech Applications Engineer for more details.
- 4 Mass listed is for the standard stage option (no brake and no tabletop). Consult Aerotech if brake and tabletop masses are desired.

Specifications		APR200DR-155	APR200DR-185	APR260DR-160	APR260DR-180		
Travel		Continuous (Optional 270° Max Limited)					
-E1, -E2, -E3, -E4	-E1, -E2, -E3, -E4	Uncalibrated	33 arc sec		25 arc sec		
Accuracy	Feedback Options	Calibrated	3 arc sec		2 arc sec		
Accuracy	-E5, -E6 Feedback	Uncalibrated	3 arc	3 arc sec		2 arc sec	
	Options	Calibrated	1.75 a	1.75 arc sec		c sec	
Resolution (Minimum	n Incremental Motion)		0.06 a	rc sec	0.04 a	rc sec	
Repeatability (Bi-Dire	ectional)¹		1 arc	sec	0.75 a	rc sec	
Repeatability (Uni-Di	rectional)		0.5 arc sec				
Total Tilt Error Motio	n²		2 arc sec				
Total Axial Error Mot	ion²		1.5 µm				
Total Radial Error Motion ²		1.5 μm					
Mandanana Guarado	With -M1 Motor Option		600 rpm		375	pm	
Maximum Speed ³	With -M2 Motor Option		800 rpm		N/A		
Aperture		75 mm		100 mm			
Maximum Torque (Co	Maximum Torque (Continuous)		11.12 Nm	15.93 Nm	19.71 Nm	29.09 Nm	
Load Capacity Axial Radial			205 kg		250 kg		
		100 kg		135 kg			
Rotor Inertia (Unloaded)		0.026 kg-m ²	0.032 kg-m ²	0.1 kg-m ²	0.12 kg-m ²		
Stage Mass ⁴		17.8 kg 22 kg 29.8 kg 35.4 k		35.4 kg			
Material		Aluminum; Hardcoat/Anodize Finish					
MTBF (Mean Time Between Failure)		20,000 hours					

- Certified with each stage.

 2 All error motion specifications are measured at 60 rpm.

 3 Maximum speed listed is stage and motor dependent (assuming a 340 V bus). Actual speed may be lower due to motor back emf or encoder bandwidth (see Encoder Bandwidth table).

 Consult an Aerotech Applications Engineer for more details.

 4 Mass listed is for the standard stage option (no brake and no tabletop). Consult Aerotech if brake and tabletop masses are desired.

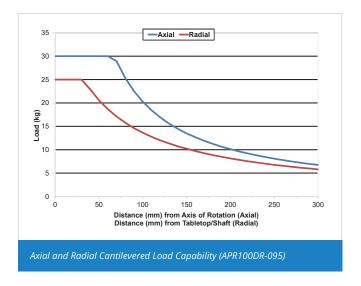
Model	Max Speed (rpm) Per Encoder Bandwidth				
Model	-E1	-E4	-E2, -E5	-E3, -E6	
APR100DR	Motor Limited	Motor Limited	147	18	
APR150DR	Motor Limited	Motor Limited	118	11	
APR200DR	Motor Limited	Motor Limited	82	8	
APR260DR	375	375	59	5	

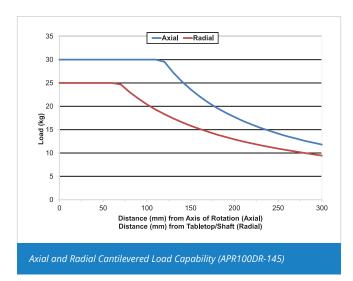
Recommended Controller		
Ballet Anti-	A3200	Ndrive HLe/Ndrive HPe/Ndrive MP10/Ndrive CP10/Npaq
Multi-Axis	Ensemble	Ensemble HLe/Ensemble HPe/Ensemble MP10/Ensemble CP10/Epaq
Single Axis Soloist		Soloist HLe/Soloist HPe/Soloist MP10/Soloist CP10

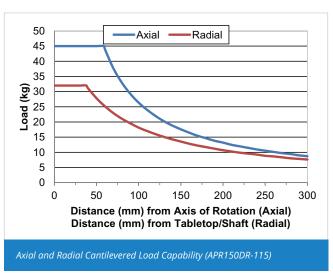
Model	APR100	DR-095	APR100DR-145		
Drive System	Slotless, brushless, direct-drive rotary motor				
Fundamental Resolution (Lines/Rev)	11840				
-E1 Resolution¹		0.028/0.0	07 arc sec		
-E2 Resolution		0.109	arc sec		
-E3 Resolution		0.014	arc sec		
-E4 Resolution		0.00030	l arc sec		
-E5 Resolution		0.109	arc sec		
-E6 Resolution		0.014	arc sec		
Maximum Bus Voltage		340	VDC		
Limit Switches	С	ptional – specified at time of	order; 5 VDC, Normally Close	ed	
Home Switch		5 VDC, Norr	nally Closed		
Model	APR150DR-115	APR150	DR-135	APR150DR-180	
Drive System		Slotless, brushless, direct-drive rotary motor			
Fundamental Resolution (Lines/Rev)	16384				
-E1 Resolution¹		0.02/0.005 arc sec			
-E2 Resolution	0.079 arc sec				
-E3 Resolution	0.0079 arc sec				
-E4 Resolution	0.000301 arc sec				
-E5 Resolution	0.079 arc sec				
-E6 Resolution	0.0079 arc sec				
Maximum Bus Voltage	340 VDC				
Limit Switches	Optional – specified at time of order; 5 VDC, Normally Closed				
Home Switch		5 VDC, Norr	nally Closed		
Model	APR200DR-155	APR200DR-185	APR260DR-160	APR260DR-180	
Drive System		Slotless, brushless, dir	ect-drive rotary motor		
Fundamental Resolution (Lines/Rev)	236	23600 32768		768	
-E1 Resolution¹	0.014/0.00	0.014/0.0034 arc sec 0.010/0.0025 arc sec			
-E2 Resolution	0.055 arc sec 0.04 arc sec			arc sec	
-E3 Resolution	0.0055 arc sec 0.004 arc sec			arc sec	
-E4 Resolution	0.000301 arc sec				
-E5 Resolution	0.055 arc sec		0.04 arc sec		
-E6 Resolution	0.0055 arc sec 0.004 arc sec			arc sec	
Maximum Bus Voltage	340 VDC				
Limit Switches	Optional – specified at time of order; 5 VDC, Normally Closed				
Home Switch	5 VDC, Normally Closed				
1 -F1 shows 4000MXU/16000MXH total multiplication	(including quadrature)		<u> </u>		

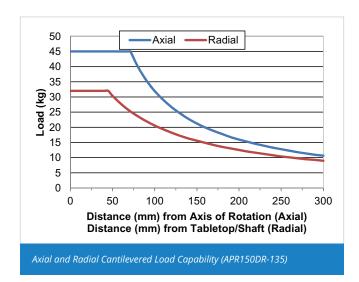
- 1 -E1 shows 4000MXU/16000MXH total multiplication (including quadrature). 2. -E5, -E6 not available with APR150DR-115.

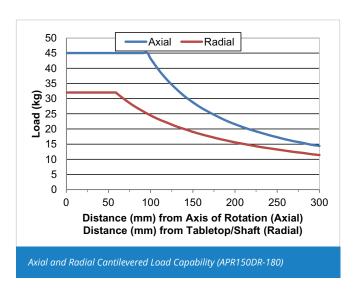


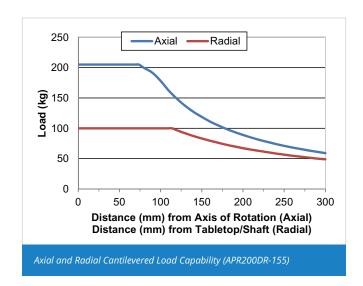


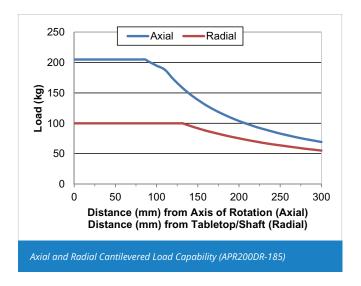


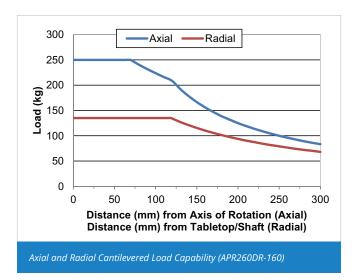


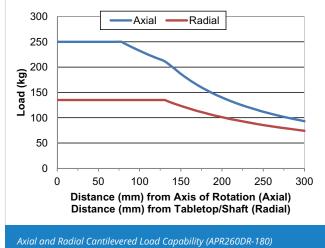


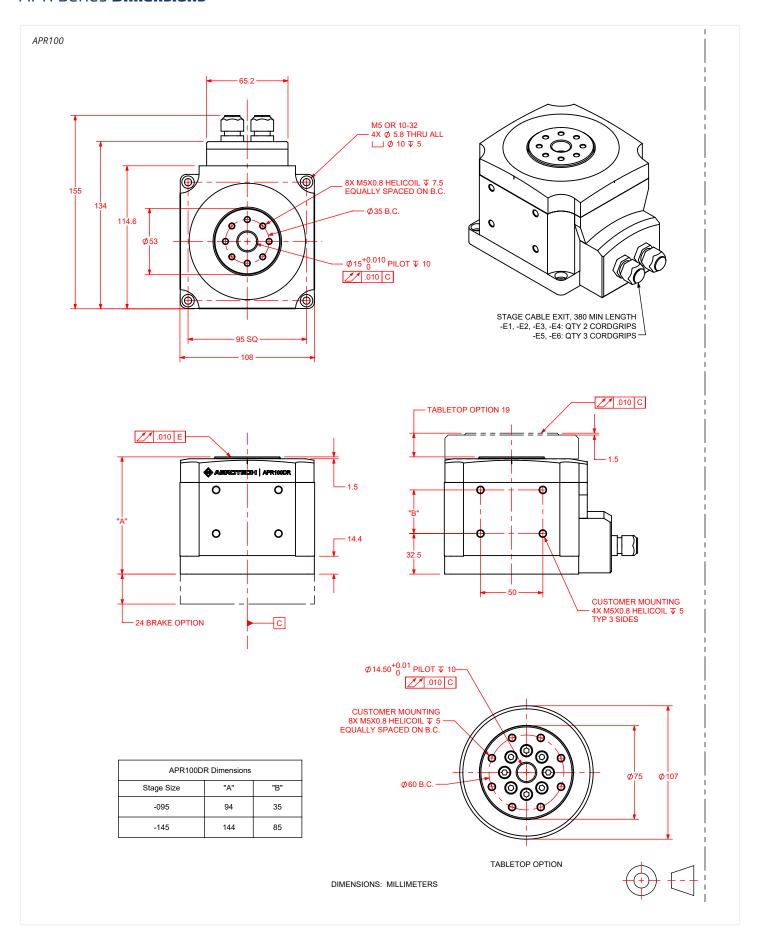


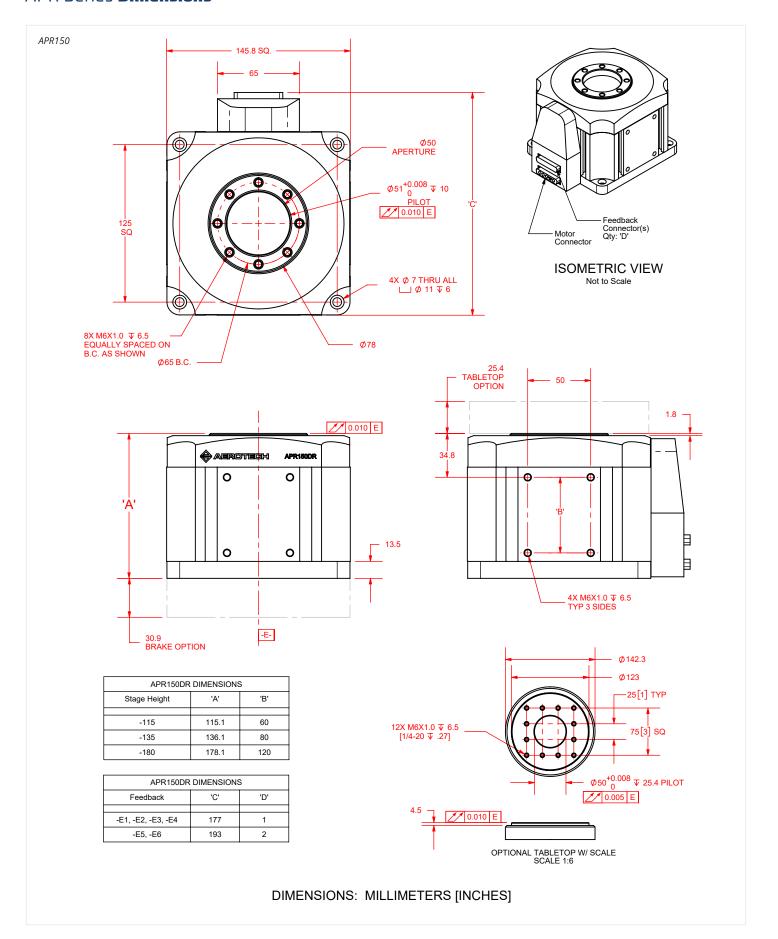


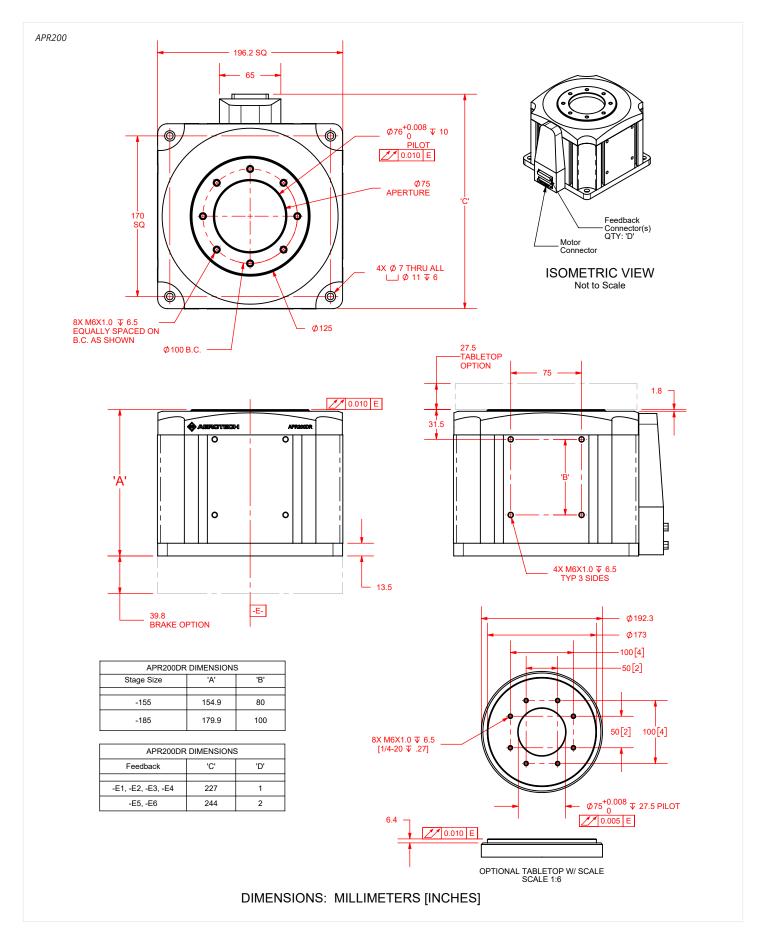


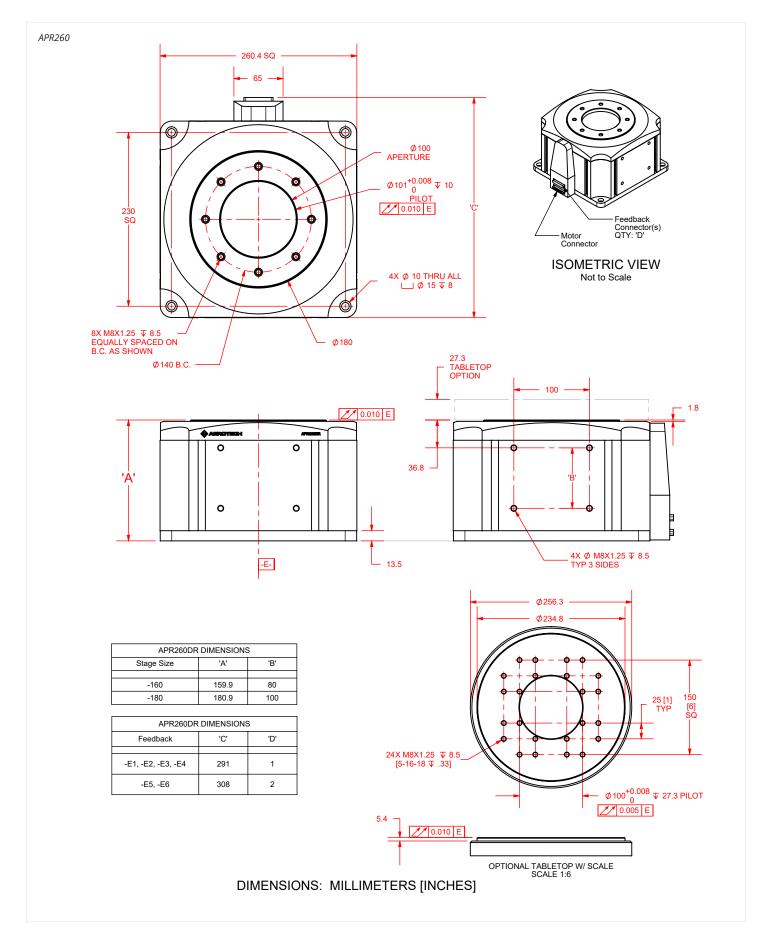












APR Series Ordering Information

APR High-Precision Mechanical Bearing Rotary Stage

APR100DR-095 APR100DR-145	APR100DR-095 high-precision mechanical bearing rotary stage APR100DR-145 high-precision mechanical bearing rotary stage
APR150DR-115	APR150DR-115 high-precision mechanical bearing rotary stage
APR150DR-135	APR150DR-135 high-precision mechanical bearing rotary stage
APR150DR-180	APR150DR-180 high-precision mechanical bearing rotary stage
APR200DR-155	APR200DR-155 high-precision mechanical bearing rotary stage
APR200DR-185	APR200DR-185 high-precision mechanical bearing rotary stage
APR260DR-160	APR260DR-160 high-precision mechanical bearing rotary stage
APR260DR-180	APR260DR-180 high-precision mechanical bearing rotary stage

Feedback (Required)

-E1	Incremental encoder, 1 Vpp
-E2	Incremental encoder, Digital RS422, x1000 interpolation
-E3	Incremental encoder, Digital RS422, x10000 interpolation
	(APR150DR, APR200DR, APR260DR); x8000 interpolation (APR100DR)
-E4	Absolute encoder
-E5	High-accuracy incremental encoder, Digital RS422, x1000 interpolation
-E6	High-accuracy incremental encoder, Digital RS422, x10000 interpolation (APR150DR, APR200DR, APR260DR); x8000 interpolation (APR100DR)

Note: -E5 and -E6 options are not available with APR150DR-115.

Motor (Required)

-M1 Low current, -A winding -M2 Low voltage, -B winding

Note: -M2 option not available with APR260DR models.

Tabletop (Optional)

-TT1 Metric graduated tabletop
-TT2 English graduated tabletop

Note: -TT2 option not available with APR100DR models.

Travel (Required)

Continuous travel
Limited travel, +/- 5 degrees
Limited travel, +/- 10 degrees
Limited travel, +/- 20 degrees
Limited travel, +/- 30 degrees
Limited travel, +/- 40 degrees
Limited travel, +/- 50 degrees
Limited travel, +/- 60 degrees
Limited travel, +/- 70 degrees
Limited travel, +/- 80 degrees
Limited travel, +/- 90 degrees
Limited travel, +/- 100 degrees
Limited travel, +/- 110 degrees
Limited travel, +/- 120 degrees
Limited travel, +/- 135 degrees

 $Note: -TRxxx\ options\ contain\ an\ extra\ 1.5\ degrees\ between\ the\ nominal\ travel\ and\ the\ electrical\ limit\ on\ each\ side.$

(Ex: -TR270 contains +/- 135 degrees of nominal travel, with +/-136.5 degrees of travel between electrical limits.)

Note: -TR010 option is not available with APR100DR.



APR Series Ordering Information

Hardstops (Optional)

-HS Mechanical hard stops

Note: -HS option requires the selection of a Tabletop option (-TTx) and a Limited Travel option (-TRxxx).

Brake (Optional)

-BK Holding brake

Note: -BK option not available with APR260DR models.

Metrology (Required)

-PL3 Metrology, uncalibrated with performance plots
-PL4 Metrology, calibrated (HALAR) with performance plots

Integration (Required)

Aerotech offers both standard and custom integration services to help you get your system fully operational as quickly as possible. The following standard integration options are available for this system. Please consult Aerotech if you are unsure what level of integration is required, or if you desire custom integration support with your system.

-TAS Integration - Test as system

Testing, integration, and documentation of a group of components as a complete system that will be used together (ex: drive, controller, and stage). This includes parameter file generation, system

tuning, and documentation of the system configuration.

-TAC Integration - Test as components

Testing and integration of individual items as discrete components. This is typically used for spare parts, replacement parts, or items that will not be used or shipped together (ex: stage only). These

components may or may not be part of a larger system.