# **Ndrive Series**

## Digital Servo Amplifiers - PWM

Wide output power range from 10 A peak to 200 A peak at 320 VDC

2- or 3-phase AC line input or DC input

CE approved and NRTL safety certification; follows the 2011/65/EU RoHS 2 Directive

**PWM** power stages

Digital current, velocity, and position loops for improved motion stability

Optional integrated encoder multiplier for higher throughput and reduced wiring

Flexible design provides ability to drive brushless and DC brush-type servomotors as well as stepping motors

**Encoder or resolver feedback** 







Ndrive HPe

Ndrive CP

Ndrive MP

#### New Designs Available!

We recommend the XC4e (in place of the Ndrive HPe) and the XC4 (in place of the Ndrive CP) for all new applications.

The Ndrive® family of digital servo amplifiers are high performance discrete drives used with the Automation 3200 motion controller. These drives are capable of controlling brushless, DC brush, and stepper motors over a wide range of operating voltages and currents. Based on a common architecture, Ndrive amplifiers perform both current- and position-loop closures digitally.

The use of high-performance double-precision processors allows these drives to generate ultra-smooth motion profiles. Servo system response is optimized with the use of up to eight second-order loop-shaping filters, precise time-aligned feed-forward and other proprietary techniques with loop closure rates up to 20 kHz.

The Ndrive family is offered in a number of highly efficient PWM versions. The Ndrive MP is a low power, small

footprint PWM drive ideal for space-sensitive applications. The Ndrive CP is a medium-power PWM drive capable of running directly from AC mains voltage and is optimized for cost-sensitive applications. The Ndrive HPe is the highest performance PWM drive providing a host of features not available on the other PWM drives, and is available in output current ranges from 10 A to 200 A peak.

Options for the Ndrive family include integral encoder interpolation, one- to three-axis position synchronized output (PSO), automatic brake control, digital and analog I/O expansion, absolute encoder interface, and one- or two-channel resolver interfaces. An optional dedicated ethernet port is available on the HPe drives for connection to third-party I/O expansion devices. This provides the potential to connect to a large number of I/O points typically required for PLC-type applications.

Any combination of Ndrive amplifiers may be connected to the Automation 3200 FireWire® network, allowing the system to be customized as needed.



Ndrive HPe Width: 99 mm Height: 232.4 mm



Ndrive CP Width: 63.5 mm Height: 198.2 mm



Ndrive MP Width: 41.1 mm Height: 141.2 mm

Ndrive Comparison Chart	Ndrive HPe	Ndrive CP	Ndrive MP	
PC Interface	FireWire <sub>®</sub>	FireWire <sub>®</sub>	FireWire <sub>®</sub>	
Current Output, Peak(1)	150-200 A	10-30 A	10 A	
Current Output, Continuous(1)	5-75 A	5-10 A	5 A	
Bus Voltage	±10-320 VDC	±10-320 VDC	±40 VDC	
Amplifier Type	PWM	PWM	PWM	
Motor Supply Voltage	2 or 3 Phase AC	2 Phase AC	DC	
Standard I/O <sub>(2)</sub>	4-DO/6-DI 1-AO/1-AI	4-DO/6-DI 1-AO/1-AI	1-Al	
Expansion I/O <sub>(2)</sub> (Additional to Base I/O)	16-DO/16-DI 3-AO/3-AI	16-DO/16-DI 1-AO/1-AI	8-DO/8-DI 1-AO/1-AI	
Single Axis PSO <sub>(3)</sub>	Yes	Yes	Yes	
Dual Axis PSO <sub>(3)</sub>	Yes	No	No	
Triple Axis PSO <sub>(3)</sub>	Yes	No	No	
Ethernet Capable for Third-Party I/O	Yes	No	No	

- 1. Peak value of the sine wave; rms current for AC motors is 0.707 \* A<sup>ca</sup>.

  2. DO = Digital Output; DI = Digital Input; AO = Analog Output; AI = Analog Input.

  3. PSO not available on Ndrive CP/MP when using integral MXU.

### **Ndrive HPe Series SPECIFICATIONS**

Ndrive HPe	Units	10	20	30	50	75	100	150	200
Motor Style		Brush, Brushless, Stepper <sup>(1)</sup>							
Motor Supply	VAC	Single-Phase 7-240 V; 50/60 Hz Single- or Three-Phase 115 or 230 V; 50/60 Hz					60 Hz		
Control Supply <sup>(2)</sup>	VAC	85-240 VAC; 50/60 Hz							
Bus Voltage <sup>(3)</sup>	VDC				10-3	320 <sup>(3)</sup>			
Peak Output Current (1 sec)(4)	A <sub>pk</sub>	10	20	30	50	75	100	150	200
Continuous Output Current <sup>(4)</sup>	A <sub>pk</sub>	5	10	10	25	37	50	75	75
Digital Inputs				6 Op	tically-Isolate	ed (2 High S	peed)		
Digital Outputs		4 Optically-Isolated							
Analog Inputs				Oi	ne 16-bit Diff	ferential; ±10	) V		
Analog Outputs		One 16-bit Single-Ended; ±10 V							
Dedicated Axis I/O on Feedback Connector		Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Speed differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input							
Dedicated I/O on Auxiliary Feedback Connector		sin, cos, mkr for Aux Enc; Aux Enc can be used for PSO Output							
I/O Expansion Board <sup>(5)</sup>		16/16 Digit	al Opto-Isola	ted; 3 Analo	og In (±10 V,	16-bit Differ	rential); 3 An	alog Out (±1	0 V, 16-bit)
High Speed Data Capture					Yes (50 n	s Latency)			
Automatic Brake Control					Standard;	24 V at 1 A			
Emergency Stop Sense Input (ESTOP)(6)		Standard; 24 V Opto-Isolated							
Position Synchronized Output (PSO)		Single Axis Standard, Two/Three Axis Optional							
Can Output Multiplied Encoder		Yes							
Can Output Square Wave Encoder		Yes							
Primary Encoder Input Frequency		500 kHz Amplified Sine Wave Standard (for onboard multiplier); 40 MHz TTL Square Wave							
Secondary Encoder Input Frequency		32 MHz Square Wave							
Encoder Multiplication		Up to x65536 with Quadrature Output (MXH)							
Absolute Encoder		Renishaw Resolute BiSS; EnDat 2.1; EnDat 2.2							
Resolver Interface		Optional; 1 or 2 Channel; 16-bit							
Internal Shunt Resistor		40 W Continuous; 400 W Peak (5 seconds)							
External Shunt		Optional							
Ethernet		Optional							
USB		No							
RS-232		No							
FireWire		Yes							
Fieldbus		Modbus TCP on PC							
Current Loop Update Rate	kHz	20							
Servo Loop Update Rate	kHz	8							
Power Amplifier Bandwidth	kHz	Selectable Through Software							
Minimum Load Inductance	mH	0.1 @ 160 VDC (1.0 mH @ 320 VDC)							
Operating Temperature	°C	0 to 50							
Storage Temperature	°C	-30 to 85							
Weight	kg (lb)		2.36 (5.2)			6.64 (14.6)		11.06	(24.4)
Standards		CE approved, NRTL safety certification, 2011/65/EU RoHS 2 Directive							
Notes:									

- Notes:

  1. For stepper motors only, one-half of bus voltage is applied across the motor (e.g., 80 VDC supply results in 40 VDC across stepper motor).

  2. "Keep Alive" supply.

  3. Output voltage dependent upon input voltage.

  4. Peak value of the sine wave; rms current for AC motors is 0.707 \* Apk.

  5. Requires IO option.

  6. Requires external relay to remove motor supply power.

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### **Ndrive CP Series SPECIFICATIONS**

Ndrive CP	Units	10	20	30	
Motor Style		Brush, Brushless, Stepper <sub>(1)</sub>			
Motor Supply	VAC	Single-Phase 7-240 VAC; 50/60 Hz			
Control Supply <sub>(2)</sub>	VAC	85-240 VAC; 50/60 Hz			
Bus Voltage <sub>(3)</sub>	VDC	10-320 <sub>(3)</sub>			
Peak Output Current (1 sec) <sub>(4)</sub>	A <sub>pk</sub>	10	20	30	
Continuous Output Current <sub>(4)</sub>	A <sub>pk</sub>	5	10	10	
Digital Inputs	T - T		6 Optically-Isolated (2 High Speed	)	
Digital Outputs		4 Optically-Isolated			
Analog Inputs	T - 1	One 16-bit Differential; ±10 V			
Analog Outputs	T - T		One 16-bit Single-Ended; ±10 V		
Dedicated Axis I/O on Feedback Connector		Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Speed differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input			
Dedicated I/O on Auxiliary Feedback Connector		sin, cos, mkr for Aux Enc; Aux Enc can be used for PSO Output			
I/O Expansion Board <sub>(5)</sub>	1 – 1	16/16 Digital Opto-Isolated; 1 Analog In (±10 V, 12-bit Differential); 1 Analog Out (±10 V, 16-bit)			
High Speed Data Capture			Yes (50 ns Latency)		
Automatic Brake Control	1 – 1	Standard; 24 V at 1 A			
Emergency Stop Sense Input (ESTOP)(6)	T - 1	Standard; 24 V Opto-Isolated			
Position Synchronized Output (PSO)	T - T	Single Axis Only			
Can Output Multiplied Encoder		No			
Can Output Square Wave Encoder		Yes			
Primary Encoder Input Frequency		200 kHz Amplified Sine Wave Standard (for onboard multiplier); 40 MHz TTL Square Wave			
Secondary Encoder Input Frequency		40 MHz Square Wave			
Encoder Multiplication	T - I	Up to x4096 (MXU)			
Absolute Encoder		Renishaw Resolute BiSS; EnDat 2.1; EnDat 2.2			
Resolver Interface		N/A			
Internal Shunt Resistor		40 W Continuous; 400 W Peak (5 seconds)			
External Shunt		Optional			
Ethernet	<b>1</b> – 1	N/A			
USB		No			
RS-232		No			
FireWire		Yes			
Fieldbus	1 1	Modbus on PC			
Current Loop Update Rate	kHz	20			
Servo Loop Update Rate	kHz	8			
Power Amplifier Bandwidth	kHz	Selectable Through Software			
Minimum Load Inductance	mH	0.1 @ 160 VDC (1.0 mH @ 320 VDC)			
Operating Temperature	°C	0 to 50			
Storage Temperature	°C	-30 to 85			
Weight	kg (lb)	1.64 (3.6)			
Standards		CE approved, NRTL safety certification, 2011/65/EU RoHS 2 Directive			

- Notes:

  1. For stepper motors only, one-half of bus voltage is applied across the motor (e.g., 80 VDC supply results in 40 VDC across stepper motor).

  2. "Keep Alive" supply.

  3. Output voltage dependent upon input voltage.

  4. Peak value of the sine wave; rms current for AC motors is 0.707 \* Apk.

  5. Requires IO option.

  6. Requires external relay to remove motor supply power.

### **Ndrive MP Series SPECIFICATIONS**

Ndrive MP	Units		
Motor Style		Brush, Brushless, Stepper <sub>(1)</sub>	
Motor Supply	VDC	10-80	
Control Supply <sub>(2)</sub>	VDC	24-80	
Bus Voltage <sub>(3)</sub>	VDC	10-80	
Peak Output Current (1 sec) <sub>(4)</sub>	A <sub>pk</sub>	10	
Continuous Output Current <sub>(4)</sub>	A <sub>pk</sub>	5	
Digital Inputs		N/A	
Digital Outputs	<u> </u>	N/A	
Analog Inputs	_	One 12-bit Differential; ±10 V	
Analog Outputs	_	N/A	
Dedicated Axis I/O on Feedback Connector		Three Limit Inputs (CW, CCW, Home); Three Hall Effect Inputs (A, B, C); Three High-Speed differential Inputs (sin, cos, mkr for encoder); Motor Over-Temperature Input	
Dedicated I/O on Auxiliary Feedback Connector		N/A	
I/O Expansion Board	_	8/8 Digital Opto-Isolated; 1 Analog In (±10 V, 12-bit Differential); 1 Analog Out (±5 V, 16-bit); sin, cos, mrk for Aux Enc; Aux Enc can be used for PSO Output	
High Speed Data Capture		Yes (50 ns Latency)	
Automatic Brake Control	<u> </u>	$Optional_{(6)}$	
Emergency Stop Sense Input (ESTOP) <sub>(6)</sub>	<u> </u>	Standard; 24 V Opto-Isolated	
Position Synchronized Output (PSO)	_	Optional <sub>(5)</sub>	
Can Output Multiplied Encoder		No	
Can Output Square Wave Encoder		No	
Primary Encoder Input Frequency		200 kHz Amplified Sine Wave Standard (for onboard multiplier); 40 MHz TTL Square Wave	
Secondary Encoder Input Frequency		32 MHz Square Wave	
Encoder Multiplication	_	Up to x1024 (MXU)	
Resolver Interface	_	N/A	
Internal Shunt Resistor		N/A	
External Shunt		N/A	
Ethernet	_	N/A	
USB		No	
RS-232		No	
FireWire		Yes	
Fieldbus		Modbus TCP on PC	
Current Loop Update Rate	kHz	20	
Servo Loop Update Rate	kHz	8	
Power Amplifier Bandwidth	kHz	Selectable Through Software	
Minimum Load Inductance	mH	0.1 @ 80 VDC	
Operating Temperature	°C	0 to 50	
Storage Temperature	°C	-30 to 85	
Weight	kg (lb)	0.45 (1.0)	
Standards		CE approved, NRTL safety certification, 2011/65/EU RoHS 2 Directive	

- Notes:

  1. For stepper motors only, one-half of bus voltage is applied across the motor (e.g., 80 VDC supply results in 40 VDC across stepper motor).

  2. "Keep Alive" supply.

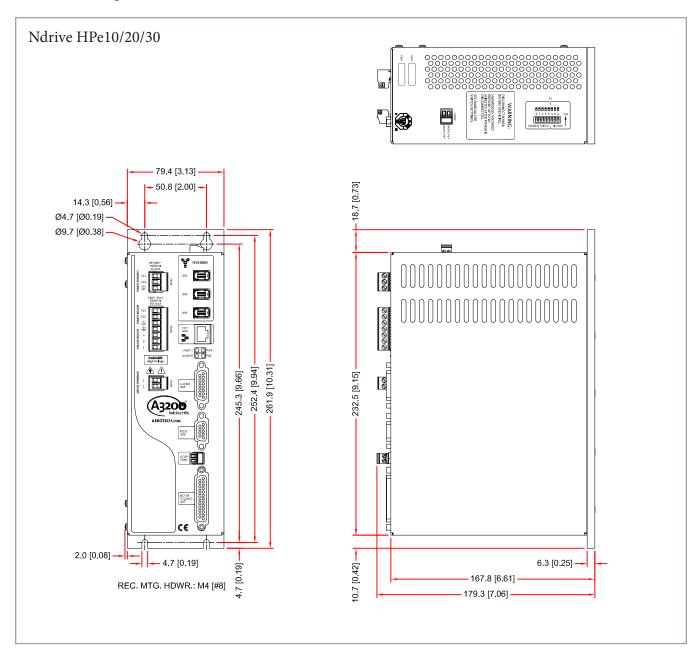
  3. Output voltage dependent upon input voltage.

  4. Peak value of the sine wave; rms current for AC motors is 0.707 \* Apk.

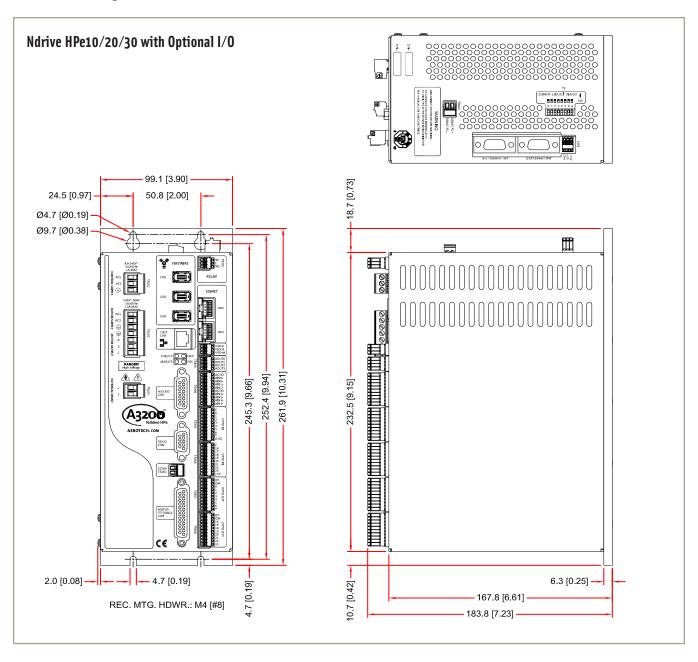
  5. Requires IO option.

  6. Requires external relay to remove motor supply power.

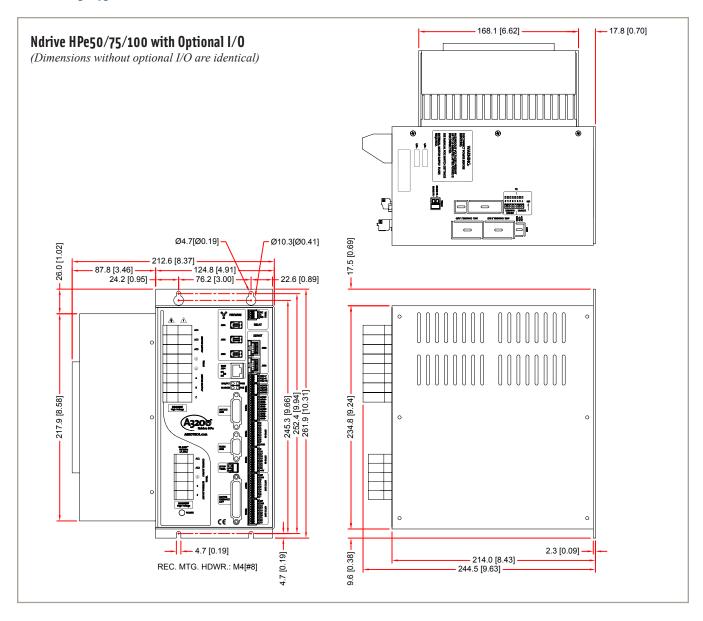
### Ndrive HPe10/20/30 DIMENSIONS



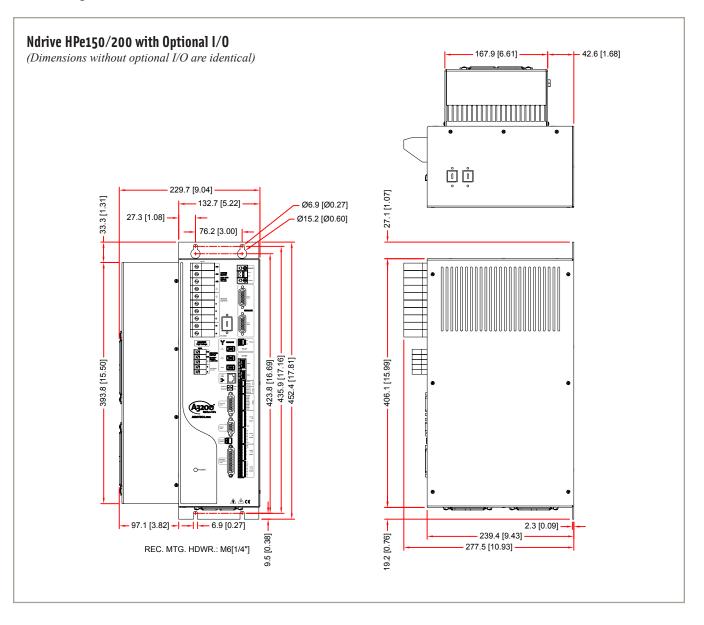
#### Ndrive HPe10/20/30 DIMENSIONS

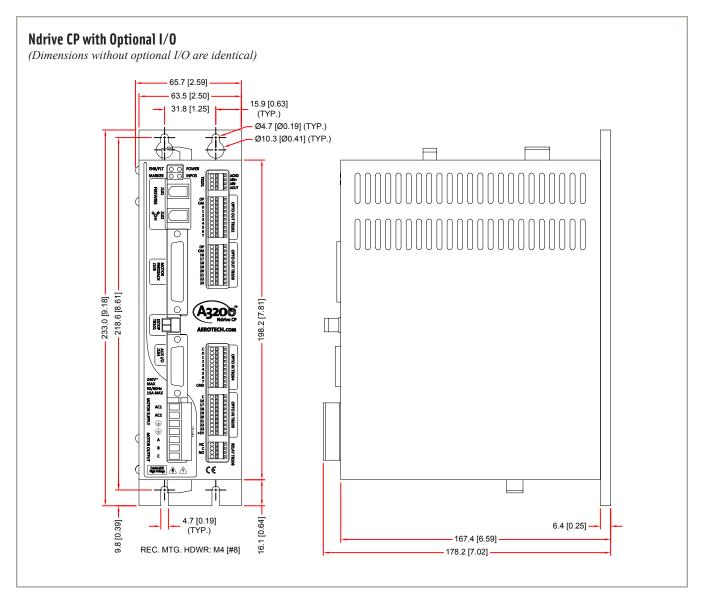


#### Ndrive HPe50/75/100 DIMENSIONS

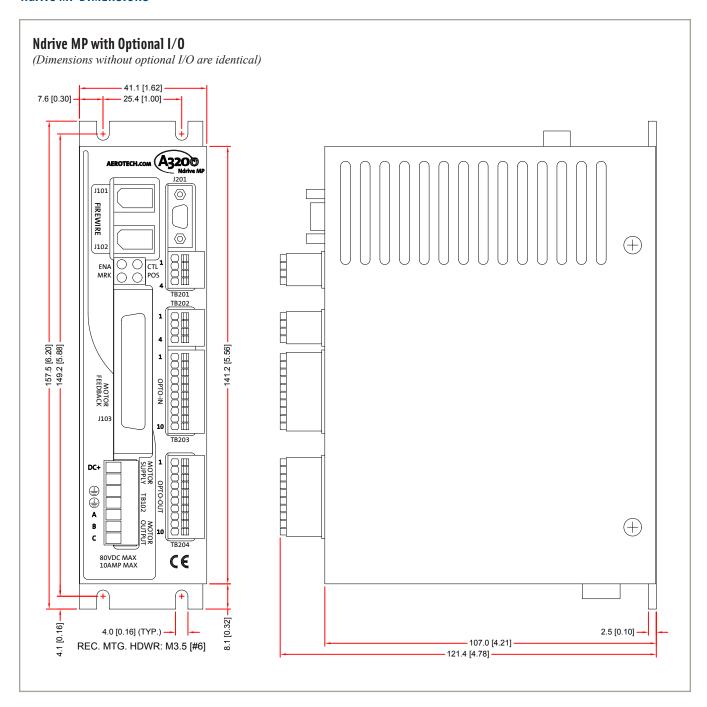


#### Ndrive HPe150/200 DIMENSIONS





#### **Ndrive MP DIMENSIONS**



#### **Ndrive Ordering Information**

Visit Aerotech's website for complete ordering information.